

EMCH 12

HOMWORK ASSIGNMENT-3

13.8

Angular velocity varies as $\dot{\theta} = 8 - 12t^2$ rad/s

To find \vec{a} at $t=0$ and $t=1$ sec for point B

(i) At $t=0$:

$$\dot{\theta} = 8 \text{ rad/s}$$

$$\ddot{\theta} = -24t = 0$$

$$a_n = R\dot{\theta}^2 \quad a_t = R\ddot{\theta} \quad (\dot{r}=0 \text{ for circular motion})$$

$$a_n = (1 \text{ m})(8 \text{ rad/s})^2 = 64 \text{ m/s}^2$$

$$a_t = 0$$

$$\therefore |\vec{a}| = 64 \text{ m/s}^2$$

(ii) At $t=1$ sec, $\dot{\theta} = 8 - 12(1)^2 = -4$ rad/s

$$\ddot{\theta} = -24(1) = -24 \text{ rad/s}^2$$

$$a_n = R\dot{\theta}^2 = (1 \text{ m})(-4 \text{ rad/s})^2 = 16 \text{ m/s}^2$$

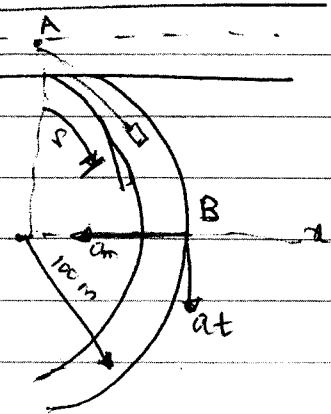
$$a_t = R\ddot{\theta} = (1 \text{ m})(-24) = -24 \text{ m/s}^2$$

$$|\vec{a}| = \sqrt{16^2 + (-24)^2} = 28.84 \text{ m/s}^2$$

13.14

$$a_t = \frac{(90 + s)}{450} \text{ m/s}^2$$

To find: Acceleration vector at B.



$$s \text{ from A to B} = \frac{\pi R}{2}$$

$$= \frac{\pi \times 100 \text{ m}}{2} = 157.08 \text{ m}$$

$$a_t(B) = \frac{(90 + 157.08)}{450} = 0.5491 \text{ m/s}^2$$

$$a_n = \frac{v^2}{\rho}$$

To find v : $a_t = \frac{v dv}{ds}$

$$\Rightarrow \frac{(90 + s)}{450} ds = v dv \quad \text{[Plugg in the expression]}$$

Integrating both sides

$$\frac{s}{5} + \frac{s^2}{900} + C = \frac{v^2}{2}$$

At A, $s=0$, $v=0$ $\therefore C=0$

$$\therefore \frac{2s}{5} + \frac{s^2}{450} = v^2$$

At $s = 157.08 \text{ m}$ (At B) $v = 10.85 \text{ m/s}$

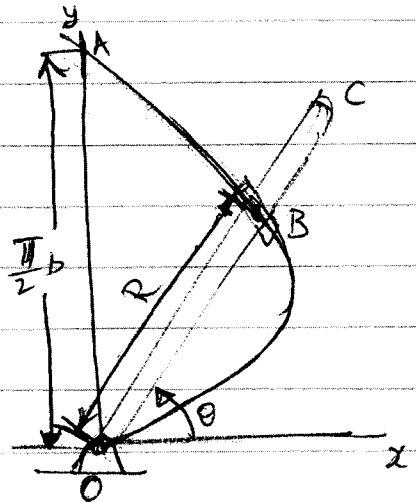
$$a_n(B) = \frac{v^2}{\rho} = \frac{(10.85)^2}{100} = 1.177 \text{ m/s}^2$$

$$\vec{a} = -1.177 \hat{i} - 0.5491 \hat{j} \text{ m/s}^2 \text{ (Taking into account directions)}$$

B330 Shape of spiral $R = b\theta$
Constant speed = v_0

To find: Angular speed $\dot{\theta}$ in terms of v_0 , b and θ .

We know that $V_R = \dot{R}$ and $V_\theta = R\dot{\theta}$



Also given $V = \sqrt{V_R^2 + V_\theta^2} = v_0 = \text{constant}$

$$R = b\theta$$

$$V_R = \dot{R} = b\dot{\theta}$$

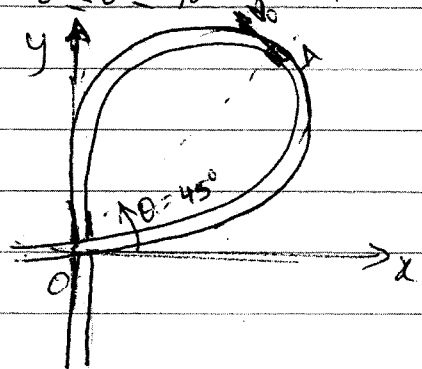
$$V = \sqrt{b^2\dot{\theta}^2 + R^2\dot{\theta}^2} = v_0$$

$$\therefore \dot{\theta} = \frac{v_0}{\sqrt{R^2 + b^2}} = \frac{v_0}{\sqrt{b^2\theta^2 + b^2}}$$

$$\therefore \dot{\theta} = \frac{v_0}{b\sqrt{\theta^2 + 1}}$$

13.34

Curve defined by $R^2 = b^2 \sin 2\theta$ $0 \leq \theta \leq 90^\circ$
Constant speed = V_0



To find: Acceleration.

$$a_R = (\ddot{R} - R\dot{\theta}^2)e_R$$

$$a_\theta = (R\ddot{\theta} + 2\dot{R}\dot{\theta})e_\theta$$

$$R^2 = b^2 \sin 2\theta$$

Differentiating

$$2RR\dot{\theta} = b^2 2\cos 2\theta \cdot \dot{\theta}$$

At $R=b$, $\theta=45^\circ$, (for position A)

$$2RR\dot{\theta} = 0 \Rightarrow \dot{R} = 0$$

$$\cancel{2RR\dot{\theta}} = b^2 \cancel{2} \cos 2\theta \dot{\theta}$$

Differentiating

$$R\ddot{R} + \dot{R}^2 = -2b^2 \sin 2\theta \dot{\theta}^2 + b^2 \cos 2\theta \dot{\theta}^2$$

At $R=b$, $\theta=45^\circ$

$$\dot{R} = -2b\dot{\theta}^2$$

$$V = \text{constant} = \sqrt{\dot{R}^2 + R^2\dot{\theta}^2} = V_0 \quad \text{At A, } \dot{R} = 0$$

$$\therefore R\dot{\theta}^2 = V_0^2$$

$$\dot{\theta}^2 = \frac{V_0^2}{R^2} = \frac{V_0^2}{b^2} \Rightarrow \boxed{\dot{\theta} = \frac{V_0}{b}}$$

$$|V| = \sqrt{\dot{R}^2 + R^2 \dot{\theta}^2} = \dot{R} \operatorname{cosec} \theta.$$

Since the velocity is only in the vertical direction
(only linear) the acceleration is the derivative
of velocity

$$\begin{aligned} a = \dot{v} &= (\dot{R} \operatorname{cosec} \theta)' = -\dot{R} \dot{\theta} \cot \theta \operatorname{cosec} \theta \\ &= -\dot{R} \left(\frac{\dot{R}}{R \sec \theta \tan \theta} \right) \cot \theta \operatorname{cosec} \theta \\ &= -\frac{\dot{R}^2}{R} \cot^3 \theta. \end{aligned}$$

Hence $\ddot{R} = -\frac{2bV_0^2}{b^2}$

To find $\dot{\theta}^2$

$$V_0^2 = \dot{R}^2 + R^2 \dot{\theta}^2$$

Differentiating

$$0 = 2\dot{R}\ddot{R} + 2R\dot{\theta}\dot{\theta}^2 + 2R^2\ddot{\theta} \Rightarrow$$

But since $\dot{R} = 0$, $\ddot{\theta}$ has to be zero.

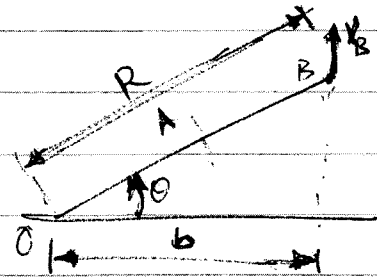
$$\text{Now } a_p = (\ddot{R} - R\dot{\theta}^2) = \left(-\frac{2V_0^2 \cdot b}{b^2} - \frac{bV_0^2}{b^2} \right) = -\frac{3V_0^2}{b}$$

$$\text{And } a_\theta = (R\ddot{\theta} + 2\dot{R}\dot{\theta}) = 0 + 0 = 0$$

$$\text{Acceleration} = -\frac{3V_0^2}{b}$$

12-38

$$\frac{b}{R} = \cos\theta$$



To find: Expressions for magnitudes of velocity and acceleration

$$R = b \sec\theta$$

Differentiating: $\dot{R} = b \sec\theta \cdot \tan\theta \cdot \dot{\theta}$

$$\Rightarrow \dot{\theta} = \frac{\dot{R}}{b \sec\theta \tan\theta}$$

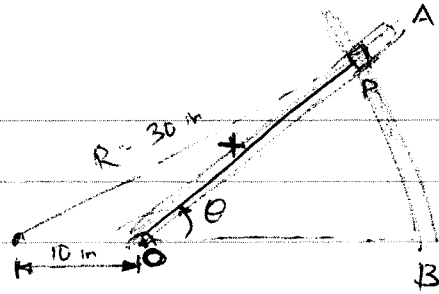
$$v = \dot{R}e_R + R\dot{\theta}e_\theta = \dot{R}e_R + \frac{\dot{R}}{\sec\theta \tan\theta} e_\theta$$

$$= \dot{R}e_R + \dot{R} \cot\theta e_\theta$$

13:40

$$\dot{\theta} = 2 \text{ rad/s}$$

To find Speed of P at $\theta = 60^\circ$



We can find the components of velocity with respect to O

$$V_R = \dot{x} \quad ; \quad V_\theta = x\dot{\theta}$$

Using the cosine law

$$\cos(\pi - \theta) = \frac{x^2 + 10^2 - 30^2}{2(x)(10)}$$

$$\Rightarrow -\cos\theta = \frac{x^2 + 10^2 - 30^2}{20x}$$

$$\Rightarrow x^2 - 800 + 20x\cos\theta = 0 \quad \text{--- (1) [simplifying the above expression]}$$

At $\theta = 60^\circ$, we can solve for x

$$x^2 + 10x - 800 = 0$$

$$\text{Solving } x = 23.72 \text{ in}$$

Now we can differentiate (1) to establish a relationship between \dot{x} and $\dot{\theta}$.

$$2x\dot{x} + 20\dot{x}\cos\theta - 20x\sin\theta\dot{\theta} = 0$$

$$\Rightarrow x\dot{x} + 10\dot{x}\cos\theta = 10x\sin\theta\dot{\theta}$$

Plugging in values of $x = 23.72$, $\dot{\theta} = 2 \text{ rad/s}$ & $\theta = 60^\circ$

$$\dot{x} (23.72 + 5) = 10 \times 23.72 \times 0.866 \times 2$$

Solving for \dot{x} we get $\dot{x} = 14.31 \text{ in/s}$

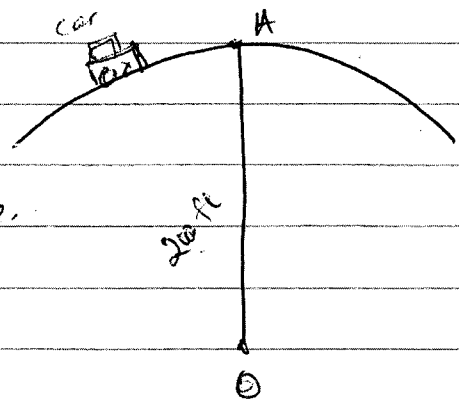
$$\text{Now } V_R = \dot{x} = 14.31 \text{ in/s}$$

$$V_\theta = r\dot{\theta} = 83.72 \times 2 = 47.44 \text{ in/s}$$

$$\therefore |V| = \sqrt{V_\theta^2 + V_R^2} = 49.54 \text{ in/s} = \text{Speed}$$

13.50 Weight of car = not specified

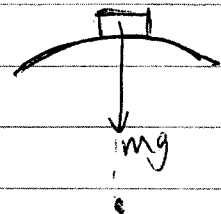
For the maximum speed v , the car is just in touch with the surface. Hence the car is on the point of losing contact - hence the normal reaction tends to zero.



The acceleration of the car has two components

$$a_n = \frac{v^2}{R} \quad a_t = \dot{v}$$

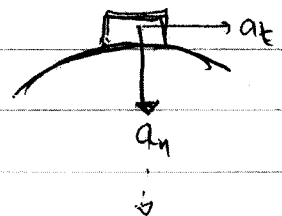
At point A, the weight acts radially towards O



Using the diagrams we can relate

$$mg = ma_n$$

$$\therefore mg = \frac{mv^2}{R}$$



$$\therefore V^2 = Rg$$

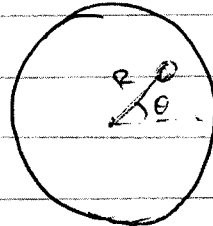
$$\therefore V = \sqrt{Rg} = \sqrt{200 \times 32.2} = 80.24 \text{ ft/sec}$$

13.56

$$R = 15 \text{ in and } \theta = 0$$

$$\mu = 0.2$$

$$\ddot{\theta} = 1.5 \text{ rad/s}^2$$



To find: Angular velocity $\dot{\theta}$

Since the coin is in a state of impending slip R is constant.

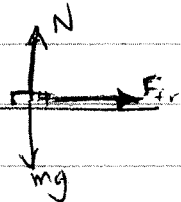
$$\text{Hence } \dot{R} = \ddot{R} = 0$$

We have the components of acceleration

$$\vec{a}_* = (\ddot{R} - R\dot{\theta}^2) \hat{e}_R + (R\ddot{\theta} + 2\dot{R}\dot{\theta}) \hat{e}_\theta$$

However it simplifies to

$$\vec{a} = (-R\dot{\theta}^2) \hat{e}_R + (R\ddot{\theta}) \hat{e}_\theta$$



The frictional force acts to oppose the net motion of the coin and is hence in a direction opposite to that of motion.

On the point of motion

$$F_{fr} = \mu N = \mu mg \quad (\text{using the FBD})$$

$$\text{Equating } \vec{F}_{fr} = m\vec{a}$$

acceleration has a resultant magnitude

$\sqrt{R\ddot{\theta}^4 + R^2\ddot{\theta}^2}$ along a direction opposite to that of friction

$$\therefore \mu mg = m \sqrt{R\ddot{\theta}^4 + R^2\ddot{\theta}^2}$$

Plugging in the known values we can solve for $\ddot{\theta}$ as

$$\ddot{\theta} = \left[\frac{1}{R^2} \left\{ (\mu g)^2 - R^2 \ddot{\theta}^2 \right\} \right]^{1/4}$$

$$= 2.22 \text{ rad/s}^2$$

13.58

mass = 2 kg

constant angular speed $\dot{\theta} = 6 \text{ rad/s}$

$\dot{r} = 0.8 \text{ m/s}$

To find: Tension and contact force at $R_0 = 1.2 \text{ m}$

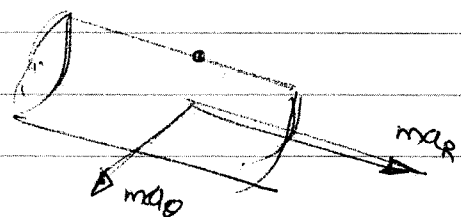
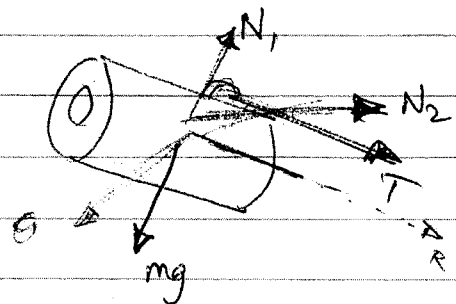
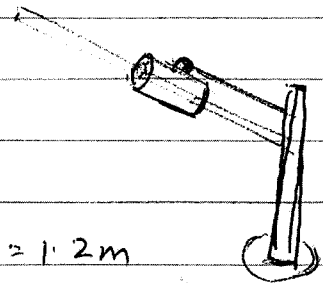
From the FBD and MAD

$$N_1 = mg = 2 \times 9.8 = 19.6 \text{ N}$$

$$F_0 = N_2 = m (r\ddot{\theta} + 2r\dot{\theta})$$

$\ddot{\theta} = 0$ - constant angular speed.

\therefore Plugging in known values



we get $N_2 = 2(2(0.8)(6)) = 19.2 \text{ N}$.

The resultant contact force has a magnitude

$$|\vec{N}| = \sqrt{N_1^2 + N_2^2} = \sqrt{(19.6)^2 + (19.2)^2} = 27.5 \text{ N}$$

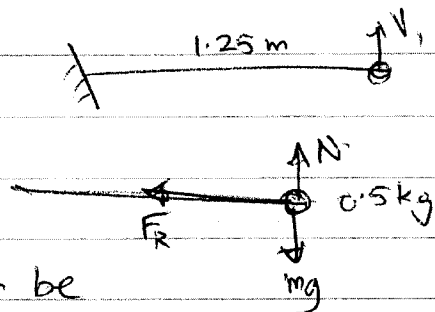
Also T is the only radial force and so

$$\begin{aligned} F_r = T &= m(\dot{\theta}^2 - r\ddot{\theta}^2) \\ &= 2(0 - 1.2 \times 36) = -86.4 \text{ N} \end{aligned}$$

Hence T has a magnitude = 86.4 N .

13.64 $k = 100 \text{ N/m}$
 $L_0 = 0.75 \text{ m}$

To find: v_1 for a circular path.



The forces acting on the body can be resolved as Tangential and Normal.

From FBD we find $F_t = 0$

acceleration has components

$$a_t = \dot{v} \quad \text{and} \quad a_n = \frac{v^2}{R}$$

Using $\vec{F} = m\vec{a}$ $\vec{F}_t = 0$ implies $ma_t = 0$ hence $\dot{v} = 0$
 v_1 is constant.

Also $F_r = k(L - L_0) = k(1.25 - 0.75) = ma_n$.

$$\Rightarrow 100(0.5) = 0.5 \cdot \frac{v_1^2}{1.25} \Rightarrow \text{Solving we get } v_1 = 11.18 \text{ m/s}$$